

6. Übung

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6.1 Aufgabe $A = \begin{pmatrix} 1 & \alpha \\ 0 & -1 \end{pmatrix}$, $B = \begin{pmatrix} \beta \\ 2 \end{pmatrix}$, $C = (\gamma \ 1)$, $D = \alpha$

* Ist das ZS asympt. stabil?

Eigenwerte von A: $(1-\lambda)(-1-\lambda) = 0 \Rightarrow \lambda_1 = 1$
 $\lambda_2 = -1$

$\text{Re}(\lambda_1) > 0 \rightarrow$ nicht stabil!

* Satz 7.9 (5): BIBO-stabil $\Leftrightarrow \text{Re}(p) < 0$

$H(s) = C(sI - A)^{-1} \cdot B + D \rightarrow$ D spielt keine Rolle bei BIBO-Stabilität.

$H^*(s) = C(sI - A)^{-1} \cdot B$ \leftarrow wir setzen $D = 0$

$(sI - A) = \begin{bmatrix} s-1 & -\alpha \\ 0 & s+1 \end{bmatrix}$

$(sI - A)^{-1} = \frac{1}{\det(sI - A)} \begin{bmatrix} s+1 & \alpha \\ 0 & s-1 \end{bmatrix} = \frac{1}{(s+1)(s-1)} \begin{bmatrix} s+1 & \alpha \\ 0 & s-1 \end{bmatrix}$

$H^*(s) = C(sI - A)^{-1} \cdot B = \frac{1}{(s+1)(s-1)} \cdot [\gamma \ 1] \begin{bmatrix} s+1 & \alpha \\ 0 & s-1 \end{bmatrix} \begin{bmatrix} \beta \\ 2 \end{bmatrix}$

$H^*(s) = [\gamma \ 1] \begin{bmatrix} \beta(s+1) + 2\alpha \\ 2(s-1) \end{bmatrix} \cdot \frac{1}{(s+1)(s-1)}$

$H^*(s) = \frac{\gamma\beta(s+1) + 2\alpha\gamma + 2(s-1)}{(s-1)(s+1)}$

wir müssen den instabilen Pol 1 eliminieren:

Zähler = 0 oder Zähler = $k(s-1)$

1) Zähler = $k(s-1)$: $\rightarrow \boxed{\gamma = 0} \rightarrow H^*(s) = \frac{2}{(s+1)}$
 \downarrow
 BIBO-stabil.

$$\text{oder } s(2 + \gamma\beta) + (\gamma\beta + 2\gamma\alpha - 2) = k(s-1)$$

$$\begin{cases} 2 + \gamma\beta = k \\ \gamma\beta + 2\gamma\alpha - 2 = -k \end{cases} \quad \begin{cases} \gamma\beta = -2 + k \\ \gamma\alpha = -k + 2 \end{cases} \rightarrow \boxed{\alpha = -\beta}$$

$$2) \text{ Zähler} = 0 : \begin{cases} 2 + \gamma\beta = 0 \\ \gamma\beta + 2\gamma\alpha - 2 = 0 \end{cases} \quad \begin{cases} \gamma\beta = -2 \\ \gamma\alpha = 2 \end{cases} \rightarrow \boxed{\alpha = -\beta}$$

BIBO stabil für $\alpha = -\beta$ oder $\gamma = 0$ oder $(\gamma\beta = -2 + k$ und $\gamma\alpha = -k + 2, k \in \mathbb{R})$.

→ Überprüfung:

$$\bullet \alpha = -\beta: H^*(s) = \frac{\gamma\beta(s+1) - 2\gamma\beta + 2(s-1)}{(s-1)(s+1)} = \frac{(2 + \gamma\beta)(s-1)}{(s-1)(s+1)}$$

$$H^*(s) = \frac{(2 + \gamma\beta)}{(s+1)} \Rightarrow \text{BIBO-stabil} \\ p = -1 < 0$$

$$\bullet \gamma = 0: H^*(s) = \frac{2(s-1)}{(s-1)(s+1)} = \frac{2}{(s+1)} \quad \text{BIBO-stabil}$$

$$\bullet \gamma\beta = -2 + k \text{ und } \gamma\alpha = -k + 2:$$

$$H^*(s) = \frac{(-2+k)(s+1) + 2(2-k) + 2(s-1)}{(s+1)(s-1)} =$$

$$= \frac{-2s + ks - 2 + k + 4 - 2k + 2s - 2}{(s+1)(s-1)} =$$

$$= \frac{s(-2+k+2) - k}{(s+1)(s-1)} = \frac{k(s-1)}{(s+1)(s-1)} = \frac{k}{s+1} \quad \text{BIBO stabil}$$

6.2 Aufgabe $A = -2, B = 1, C = 1, D = 1$

$$i) \phi(t) = \exp(At) = \sum_{n=0}^{\infty} \frac{(-2t)^n}{n!} = e^{-2t} //$$

$$ii) H(s) = C(sI - A)^{-1}B + D = 1 \cdot (s - (-2))^{-1} \cdot 1 + 1 = \\ = \frac{1}{s+2} + 1 = \frac{1+s+2}{s+2} = \frac{s+3}{s+2} //$$

$$\text{iii) } g(t) = v(t) \cdot C \cdot \exp(At) B + \delta(t) \cdot D$$

$$g(t) = v(t) \cdot 1 \cdot e^{-2t} \cdot 1 + \delta(t) \cdot 1 = v(t) e^{-2t} + \delta(t)$$

iv) Sprungantwort.

$$\psi(t, 0, v) = (g * v)(t) = v(t) \int_0^t e^{-2z} dz + v(t) \int_0^t \delta(z) dz$$

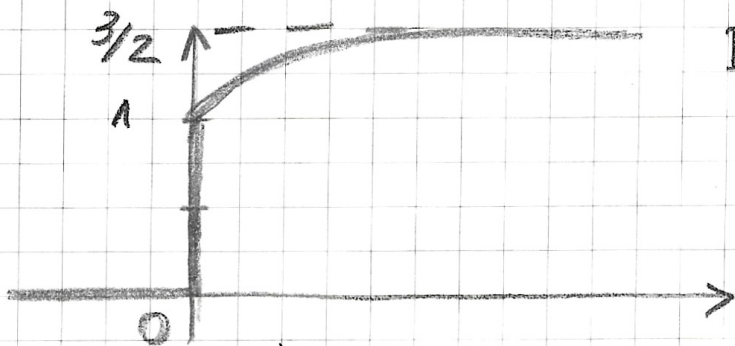
$$\begin{aligned} \psi(t, 0, v) &= v(t) \left. \frac{e^{-2z}}{-2} \right|_0^t + v(t) = \\ &= v(t) \left(1 + \frac{1}{2} - \frac{e^{-2t}}{2} \right) = v(t) \cdot \left(\frac{3}{2} - \frac{e^{-2t}}{2} \right) \end{aligned}$$

Anfangswert: $\psi(0, 0, v) = 1 \cdot \left(\frac{3}{2} - \frac{1}{2} \right) = 1 //$

(oder $s \rightarrow \infty \quad H(\infty) = \lim_{s \rightarrow \infty} \frac{s+3}{s+2} = 1$)

Endwert: $\psi(\infty, 0, v) = \lim_{t \rightarrow \infty} v(t) \left(\frac{3}{2} - \frac{e^{-2t}}{2} \right) = \frac{3}{2}$

(oder $s \rightarrow 0 \quad H(0) = \frac{3}{2}$)



$$D_1 \psi(0, 0, v) = \frac{-2}{-2} e^{-2 \cdot 0} = 1 //$$

$$D_1 \psi(0, 0, v) > 0.$$

6.3 Aufgabe $A = \begin{pmatrix} -3 & 0 \\ 0 & -1 \end{pmatrix}$, $B = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$, $C = [1 \ 0]$, $D = 0$

i) $H(s) = C(sI - A)^{-1}B + D \stackrel{0}{\rightarrow}$

$$(sI - A) = \begin{bmatrix} s+3 & 0 \\ 0 & s+1 \end{bmatrix}, \quad (sI - A)^{-1} = \frac{1}{(s+3)(s+1)} \begin{bmatrix} s+1 & 0 \\ 0 & s+3 \end{bmatrix}$$

$$H(s) = \frac{1}{(s+3)(s+1)} [1 \ 0] \begin{bmatrix} s+1 & 0 \\ 0 & s+3 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \frac{1}{(s+3)} //$$

ii) $u(t) = \cos(3t)$ $\tilde{u}(t) = \operatorname{Re}(e^{3it})$, $\tilde{u} = e^{3it}$

$$y(t) = \operatorname{Re}(\tilde{y}(t)), \quad \tilde{y}(t) = H(\lambda) \tilde{u}(t)$$

• Eigenwerte von A : $-1, -3 \neq 3i$ 1. Bedingung erfüllt ✓

$$\tilde{y}(t) = H(3i) \tilde{u}(t) \Rightarrow H(3i) = \frac{1}{3i+3} = \frac{3i-3}{3i^2-9} = \frac{-1}{6}(i-1)$$

$$H(3i) = -\frac{1}{6}(e^{\frac{\pi}{2}i} - 1) \quad (e^{ki} = \cos(k) + i \sin(k))$$

$$y(t) = \operatorname{Re}(\tilde{y}(t)) = \operatorname{Re}\left(-\frac{1}{6}(e^{\frac{\pi}{2}i} - 1) \cdot e^{3it}\right) = \operatorname{Re}\left(-\frac{1}{6}(e^{\frac{\pi}{2}+3t}i - e^{3it})\right)$$

$$y(t) = \frac{1}{6}(\cos(3t) - \cos(3t + \frac{\pi}{2})) //$$