

Steuer- und Regelungstechnik

4. Übung

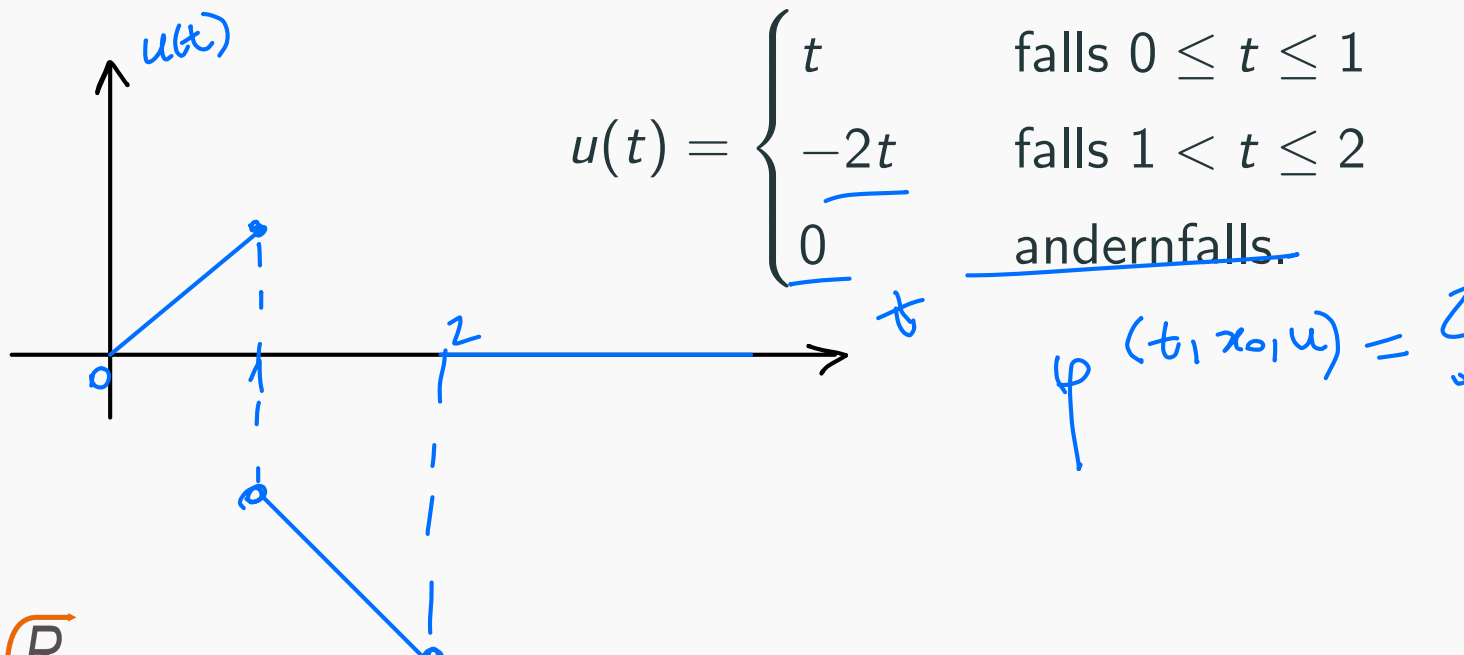
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Aufgabe 3.2

Berechnen Sie die Lösung für das Zustandssystem $\dot{x} = x + u$, das den skalaren Fall darstellt, mit der Anfangsbedingung $x_0 = -1$ und der folgenden stückweise linearen Funktion für den Eingang $u(t)$, wobei $t \in \mathbb{R}$:



Aufgabe 3.2

$$0 \leq t \leq 1 : \quad x_0 = -1, \quad u_1(t) = t, \quad \dot{x} = x + u = ax + bu$$

$a=1$ und $b=1$

$$\varphi(t, x_0, u) = e^{at} x_0 + \int_0^t e^{a(t-z)} b u(z) dz$$

$$\varphi_1(t, x_0, u_1) = e^t \cdot x_0 + \int_0^t e^{(t-z)} u_1(z) dz = -e^t + \int_0^t e^{(t-z)} z dz$$

$$= -\frac{t}{e} + \frac{e^t}{e} \int_0^t e^{-z} z dz$$

Integration durch Teile:
 $\int \alpha d\beta = \alpha\beta - \int \beta d\alpha$

$$\int e^{-z} z dz \rightarrow \left\{ \begin{array}{l} \alpha = z \rightarrow d\alpha = dz \\ d\beta = e^{-z} dz \rightarrow \beta = -e^{-z} \end{array} \right.$$

$$\varphi_1(t, x_0, u_1) = -(t+1)$$

$$\int e^{-z} z dz = z \cdot (-e^{-z}) - \int -e^{-z} dz = -\frac{z}{e^{-z}} - e^{-z} + C_1 = -e^{-z}(z+1) + C_1$$

$$\begin{aligned} \varphi_1(t, x_0, u_1) &= -e^t + e^t \left(-e^{-z}(z+1) \right) \Big|_0^t \\ &= -e^t + e^t \left(-e^{-t}(t+1) + 1 \right) \\ &= -\cancel{e^t} + \left(-\cancel{e^t} e^{-t}(t+1) + \cancel{e^t} \right) = -(t+1) \end{aligned}$$

Aufgabe 3.2

$$\varphi_1(t, \underline{x}_0, u_1) = -(t+1) \rightarrow x_1 = \varphi_1(1, x_0, u_1) = -(1+1) = -2$$

$$u_2 = -2t \quad (1 < t \leq 2)$$

$$\varphi_2(t, \underline{x}_1, u_2)$$

$$\varphi_2(t, x_1, u_2) = e^{(t-1)} \cdot x_1 + e^t \int_1^t e^{-z} (-2z) dz =$$

$$= -2e^{(t-1)} - 2e^t \int_1^t e^{-z} z dz$$

$$= -2e^{(t-1)} - 2e^t \left(-e^{-z} (z+1) \right) \Big|_1^t = -2e^{(t-1)} - 2e^t \left(-e^{-t} (t+1) + e^{-1} \cdot 2 \right)$$

$$= -2e^{(t-1)} + 2e^{(t-1)} (t+1) - 4e^{-1} e^t = e^{(t-1)}$$

$$\varphi_2(t, x_1, u_2) = -6e^{(t-1)} + 2(t+1) //$$

Aufgabe 3.2

$$\varphi_2(t, x_1, u_2) = -6e^{(t-1)} + 2(t+1) \rightarrow x_2 = \varphi_2(2, x_1, u_2) = 6(1+e) //$$

$$\varphi_3(t, x_2, u_3) = e^{(t-2)} \cdot x_2 + \int_2^t e^{(t-z)} u_3(z) dz = e^{(t-2)} \cdot \underline{x_2}$$

$$\varphi_3(t, x_2, u_3) = 6(1+e) \cdot e^{(t-2)}$$

$$\varphi(t, x_0, u) = \begin{cases} -(t+1), & 0 \leq t \leq 1 \\ -6e^{(t-1)} + 2(t+1), & 1 < t \leq 2 \\ 6(1+e)e^{(t-2)}, & \text{andernfalls.} \end{cases}$$

Aufgabe 4.1

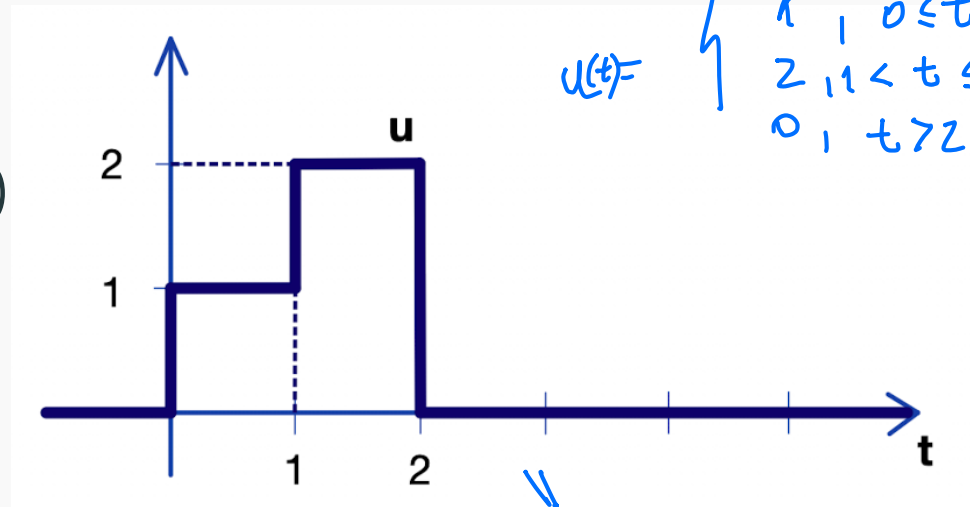
Betrachten Sie das folgende Differentialgleichungssystem

Zustandform:

$$\ddot{x}(t) = -9\dot{x}(t) - 20x(t) + u(t)$$

$$y(t) = x(t)$$

$$\underline{x(0) = 0} \quad \text{und} \quad \underline{\dot{x}(0) = 0}$$



$$u(t) = \begin{cases} 0, & t < 0 \\ 1, & 0 \leq t \leq 1 \\ 2, & 1 < t \leq 2 \\ 0, & t > 2 \end{cases}$$

Berechnen Sie das Ausgangssignal y .

$$\rightarrow u(t) = \mathcal{T}(t) + \mathcal{T}(t-1) - 2\mathcal{T}(t-2)$$

Aufgabe 4.1

$$\begin{cases} \ddot{x} = -9\dot{x} - 20x + u \\ y = x \end{cases} \xrightarrow{\text{ZS}} \begin{cases} \begin{bmatrix} \dot{x} \\ \ddot{x} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -20 & -9 \end{bmatrix} \begin{bmatrix} x \\ \dot{x} \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u \\ y = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ \dot{x} \end{bmatrix} + \begin{bmatrix} 0 \end{bmatrix} u \end{cases}$$

Impulsantwort: $g(t) = \nabla(t) \cdot C e^{At} \cdot B + \delta(t) \cdot D$

$$g(t) = \nabla(t) C e^{At} B + \delta(t) D \xrightarrow{D=0} = \nabla(t) C e^{At} B$$

$$\nabla(t) = \begin{cases} 1, & \text{falls } t \geq 0 \\ 0, & \text{sonst.} \end{cases}$$

$$g(t) = \nabla(t) [1 \ 0] e^{At} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 0 & 1 \\ -20 & -9 \end{bmatrix} \rightarrow \text{Eigenwerte: } \det(A - \lambda \text{id}) = 0 \rightarrow \det \begin{bmatrix} -\lambda & 1 \\ -20 & -9-\lambda \end{bmatrix} =$$

$$= \lambda(9+\lambda) + 20 = \lambda^2 + 9\lambda + 20 \rightarrow \begin{matrix} \lambda_1 = -4 \\ \lambda_2 = -5 \end{matrix}$$

Aufgabe 4.1

Eigenwerte $\neq 0$, A ist nicht nilpotent. $A = \begin{bmatrix} 0 & 1 \\ -20 & -9 \end{bmatrix}$

Diagonaltransformation: $A = T \Lambda T^{-1}$, $T = [v_1 \ v_2]$, $\Lambda = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} = \begin{bmatrix} -4 & 0 \\ 0 & -5 \end{bmatrix}$

$$v_1 \rightarrow Av_1 = \lambda_1 v_1 \rightarrow (A - \lambda_1 I)v_1 = 0$$

$$(A - i\lambda_1 I)v_1 = \begin{bmatrix} 4 & 1 \\ -20 & -5 \end{bmatrix} \begin{bmatrix} v_{11} \\ v_{12} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \rightarrow \begin{cases} 4v_{11} + v_{12} = 0 \\ -20v_{11} - 5v_{12} = 0 \end{cases} \rightarrow \begin{cases} v_{11} = -v_{12}/4 \\ v_1 = \begin{bmatrix} 1 \\ -4 \end{bmatrix} \end{cases}$$

$$(A - i\lambda_2 I)v_2 = \begin{bmatrix} 5 & 1 \\ -20 & -4 \end{bmatrix} \begin{bmatrix} v_{21} \\ v_{22} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \rightarrow \begin{cases} 5v_{21} + v_{22} = 0 \\ -20v_{21} - 4v_{22} = 0 \end{cases} \rightarrow \begin{cases} v_{21} = -v_{22}/5 \\ v_2 = \begin{bmatrix} 1 \\ -5 \end{bmatrix} \end{cases}$$

$$T = [v_1 \ v_2] = \begin{bmatrix} 1 & 1 \\ -4 & -5 \end{bmatrix}, \quad T^{-1} = \frac{1}{\det(T)} \begin{bmatrix} -5 & -1 \\ 4 & 1 \end{bmatrix} = (-1) \begin{bmatrix} -5 & -1 \\ 4 & 1 \end{bmatrix} = \begin{bmatrix} 5 & 1 \\ -4 & -1 \end{bmatrix}$$

$$\det(T) = -5 - (-4) = -1$$

Aufgabe 4.1

$$\therefore A = T \Lambda T^{-1} = \begin{bmatrix} 1 & 1 \\ -4 & -5 \end{bmatrix} \begin{bmatrix} -4 & 0 \\ 0 & -5 \end{bmatrix} \begin{bmatrix} 5 & 1 \\ -4 & -1 \end{bmatrix}$$

und $A^n = (T \Lambda T^{-1})^n = T \Lambda^n T^{-1} \rightarrow \Lambda^n = \begin{bmatrix} \lambda_1^n & 0 \\ 0 & \lambda_2^n \end{bmatrix}$

$$\exp(At) = \sum_{n=0}^{\infty} \frac{A^n t^n}{n!} = \sum_{n=0}^{\infty} \frac{(T \Lambda T^{-1})^n t^n}{n!} = \sum_{n=0}^{\infty} \frac{T \Lambda^n T^{-1} t^n}{n!} = T \left(\sum_{n=0}^{\infty} \frac{\Lambda^n t^n}{n!} \right) T^{-1}$$

$$= T \left(\sum_{n=0}^{\infty} \frac{\begin{pmatrix} \lambda_1^n & 0 \\ 0 & \lambda_2^n \end{pmatrix} t^n}{n!} \right) T^{-1} = T \begin{pmatrix} \sum_{n=0}^{\infty} \frac{\lambda_1^n t^n}{n!} & 0 \\ 0 & \sum_{n=0}^{\infty} \frac{\lambda_2^n t^n}{n!} \end{pmatrix} T^{-1} = T \begin{pmatrix} e^{\lambda_1 t} & 0 \\ 0 & e^{\lambda_2 t} \end{pmatrix} T^{-1}$$

$$= T \begin{pmatrix} e^{\lambda_1 t} & 0 \\ 0 & e^{\lambda_2 t} \end{pmatrix} T^{-1} = T \begin{bmatrix} e^{-4t} & 0 \\ 0 & e^{-5t} \end{bmatrix} T^{-1}$$

Aufgabe 4.1

Impulsantwort: $g(t) = \mathcal{V}(t) \begin{bmatrix} 1 & 0 \end{bmatrix} \exp(At) \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

$$g(t) = \mathcal{V}(t) \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}_{1 \times 2} T \begin{bmatrix} e^{-4t} & 0 \\ 0 & e^{5t} \end{bmatrix}_{2 \times 2} T^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$T = \begin{bmatrix} 1 & 1 \\ -4 & -5 \end{bmatrix}$$

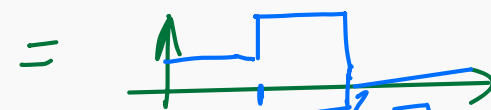
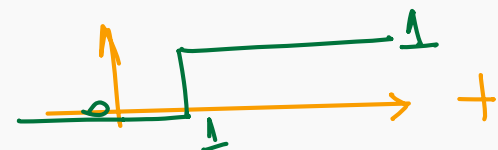
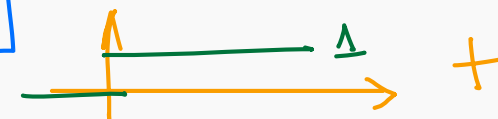
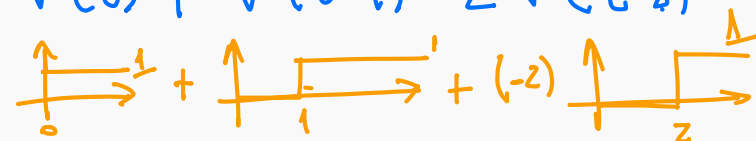
und $T^{-1} = \begin{bmatrix} 5 & 1 \\ -4 & -1 \end{bmatrix}$

$$g(t) = \mathcal{V}(t) \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} e^{-4t} & 0 \\ 0 & e^{5t} \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \mathcal{V}(t) \begin{bmatrix} e^{-4t} & e^{5t} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

3 Fällen: $0 < t < 1$, $1 < t < 2$, $2 < t$

$$g(t) = \mathcal{V}(t) (e^{-4t} - e^{5t})$$

$$\mathcal{U}(t) = \mathcal{V}(t) + \mathcal{V}(t-1) - 2\mathcal{V}(t-2)$$



Aufgabe 4.1

$$g(t) = \nabla(t) \begin{pmatrix} e^{-4t} & -e^{-5t} \end{pmatrix}$$

$$u(t) = \nabla(t) + \nabla(t-1) - 2\nabla(t-2) \quad (\text{aus der Abbildung})$$

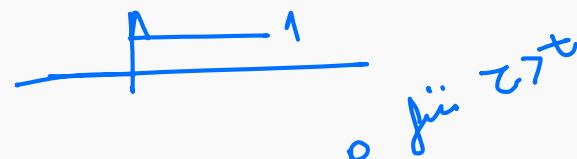
Linearität: $y(t) = \psi(t, x_0, u) = \psi(t, x_0, u_1) + \psi(t, x_0, u_2) - 2\psi(t, x_0, u_3)$

Kausalität: $\psi(t, x_0, u_1) = (g * \nabla)(t)$

Zeitinvariant: $\psi(t, x_0, u_2) = (g * \nabla)(t-2)$

$$\psi(t, x_0, u_3) = (g * \nabla)(t-2)$$

$$x_0 = \begin{bmatrix} p \\ 0 \end{bmatrix}$$



$$(g * \nabla)(t) = \int_{-\infty}^{\infty} g(\tau) \nabla(t-\tau) d\tau = \int_{-\infty}^{\infty} \nabla(\tau) \begin{pmatrix} e^{-4\tau} & -e^{-5\tau} \end{pmatrix} \nabla(t-\tau) d\tau$$

$$= \int_0^t \nabla(\tau) \begin{pmatrix} e^{-4\tau} & -e^{-5\tau} \end{pmatrix} \nabla(t-\tau) d\tau$$

für $t < 0$ für $t > 0$

Aufgabe 4.1

$$\begin{aligned}
 (y * \nabla)(t) &= \int_0^t \nabla(z) (e^{-4z} - e^{-5z}) \nabla(t-z) dz = \nabla(t) \int_0^t (e^{-4z} - e^{-5z}) dz \\
 &= \nabla(t) \left(\int_0^t e^{-4z} dz - \int_0^t e^{-5z} dz \right) = \nabla(t) \left(-\frac{e^{-4z}}{4} \Big|_0^t - \left(-\frac{e^{-5z}}{5} \right) \Big|_0^t \right) \\
 &= \nabla(t) \left(-\frac{e^{-4t}}{4} + \frac{1}{4} + \frac{e^{-5t}}{5} - \frac{1}{5} \right) = \nabla(t) \left(\frac{e^{-5t}}{5} - \frac{e^{-4t}}{4} + \frac{1}{20} \right) // \\
 \therefore y(t) &= \nabla(t) \cdot \left(\frac{e^{-5t}}{5} - \frac{e^{-4t}}{4} + \frac{1}{20} \right) + \nabla(t-1) \cdot \left(\frac{e^{-5(t-1)}}{5} - \frac{e^{-4(t-1)}}{4} + \frac{1}{20} \right) - 2 \cdot \nabla(t-2) \cdot \left(\frac{e^{-5(t-2)}}{5} - \frac{e^{-4(t-2)}}{4} + \frac{1}{20} \right)
 \end{aligned}$$