

6. Übung 21.02.22, Victor Cheidde chain

6.1 Aufgabe $A = \begin{pmatrix} 1 & \alpha \\ 0 & -1 \end{pmatrix}$, $B = \begin{pmatrix} \beta \\ 2 \end{pmatrix}$, $C = \begin{pmatrix} \gamma & 1 \end{pmatrix}$, $D = \alpha$

* Ist das ZS asympt. stabil?

Eigenwerte von A : $(1-\lambda)(-1-\lambda) = 0 \leq \lambda_1 = 1 \leq \lambda_2 = -1$

$\operatorname{Re}(\lambda_1) > 0 \rightarrow$ nicht stabil!

* Satz 7.9 (5): BIBO-stabil $\Leftrightarrow \operatorname{Re}(p) < 0$

$$H(s) = C(sI - A)^{-1} \cdot B + D \rightarrow D \text{ spielt keine Rolle bei BIBO-Stabilität.}$$

$$H^*(s) = C(sI - A)^{-1} \cdot B \quad \text{wir setzen } D = 0 \rightarrow$$

$$(sI - A) = \begin{bmatrix} s-1 & -\alpha \\ 0 & s+1 \end{bmatrix}$$

$$(sI - A)^{-1} = \frac{1}{\det(sI - A)} \begin{bmatrix} s+1 & \alpha \\ 0 & s-1 \end{bmatrix} = \frac{1}{(s+1)(s-1)} \begin{bmatrix} s+1 & \alpha \\ 0 & s-1 \end{bmatrix}$$

$$H^*(s) = C(sI - A)^{-1} \cdot B = \frac{1}{(s+1)(s-1)} \cdot \begin{bmatrix} \gamma & 1 \end{bmatrix} \begin{bmatrix} s+1 & \alpha \\ 0 & s-1 \end{bmatrix} \begin{bmatrix} \beta \\ 2 \end{bmatrix}$$

$$H^*(s) = [\gamma \ 1] \begin{bmatrix} \beta(s+1) + 2\alpha \\ 2(s-1) \end{bmatrix} \cdot \frac{1}{(s+1)(s-1)}$$

$$H^*(s) = \frac{\gamma \beta(s+1) + 2\alpha \gamma + 2(s-1)}{(s-1)(s+1)}$$

Wir müssen den instabilen Pol 1 eliminieren:

Zähler = 0 oder Zähler = K(s-1)

1) Zähler = K(s-1) : $\rightarrow \boxed{\gamma = 0} \rightarrow H^*(s) = \frac{2}{(s+1)}$

BIBO-stabil.

$$\text{oder } s(2 + \gamma\beta) + (\gamma\beta + 2\gamma\alpha - 2) = k(5-1)$$

$$\begin{cases} 2 + \gamma\beta = k \\ \gamma\beta + 2\gamma\alpha - 2 = -k \end{cases} \quad \begin{aligned} \gamma\beta &= -2 + k \Rightarrow \\ \gamma\alpha &= -k + 2 \end{aligned} \quad \boxed{\alpha = -\beta}$$

2) Zähler = 0 : $\begin{cases} 2 + \gamma\beta = 0 \\ \gamma\beta + 2\gamma\alpha - 2 = 0 \end{cases} \quad \begin{aligned} \gamma\beta &= -2 \\ \gamma\alpha &= 2 \end{aligned} \Rightarrow \boxed{\alpha = -\beta}$

BIBO stabil für $\alpha = -\beta$ oder $\gamma = 0$ oder
 $(\gamma\beta = -2 + k \text{ und } \gamma\alpha = -k + 2, k \in \mathbb{R})$.

→ Überprüfung:

$$\cdot \alpha = -\beta : H^*(s) = \frac{\gamma\beta(s+1) - 2\gamma\beta + 2(s-1)}{(s-1)(s+1)} = \frac{(2+\gamma\beta)(s-1)}{(s-1)(s+1)}$$

$$H^*(s) = \frac{(2+\gamma\beta)}{(s+1)} \Rightarrow \text{BIBO-stabil} \quad p = -1 < 0$$

$$\cdot \gamma = 0 : H^*(s) = \frac{2(s-1)}{(s-1)(s+1)} = \frac{2}{(s+1)} \quad \text{BIBO-stabil}$$

$$\cdot \gamma\beta = -2 + k \text{ und } \gamma\alpha = -k + 2 :$$

$$H^*(s) = \frac{(-2+k)(s+1) + 2(z-k) + 2(s-1)}{(s+1)(s-1)} =$$

$$= \frac{-2s + ks - 2 + k + 4 - 2k + 2s - 2}{(s+1)(s-1)} =$$

$$= \frac{s(-z+k+2) - k}{(s+1)(s-1)} = \frac{k(s-1)}{(s-1)(s+1)} = \frac{k}{s+1} \quad \text{BIBO-stabil}$$

6.2 Aufgabe $A = -2, B = 1, C = 1, D = 1$

$$\text{i) } \phi(t) = \exp(At) = \sum_{n=0}^{\infty} \frac{(-2t)^n}{n!} = e^{-2t} //$$

$$\text{ii) } H(s) = C(sI - A)^{-1}B + D = 1 \cdot (s - (-2))^{-1} \cdot 1 + 1 =$$

$$= \frac{1}{s+2} + 1 = \frac{1+s+2}{s+2} = \frac{s+3}{s+2} //$$

$$\text{iii) } g(t) = \nabla(t) \cdot C \cdot \exp(At) B + \delta(t) \cdot D$$

$$g(t) = \nabla(t) \cdot 1 \cdot e^{-2t} \cdot 1 + \delta(t) \cdot 1 = \nabla(t) e^{-2t} + \delta(t)$$

iv) Sprungantwort.

$$\psi(t, 0, \nabla) = (g * \nabla)(t) = \nabla(t) \int_0^t e^{-2z} dz + \nabla(t) \int_0^t s(z) dz$$

$$\begin{aligned} \psi(t, 0, \nabla) &= \nabla(t) \left[\frac{e^{-2z}}{-2} \right]_0^t + \nabla(t) \cdot \\ &= \nabla(t) \left(1 + \frac{1}{2} - \frac{e^{-2t}}{2} \right) = \nabla(t) \left(\frac{3}{2} - \frac{e^{-2t}}{2} \right) \end{aligned}$$

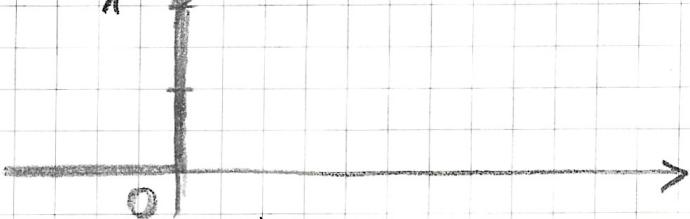
$$\text{Anfangswert: } \psi(0, 0, \nabla) = 1 \left(\frac{3}{2} - \frac{1}{2} \right) = 1 //$$

$$(\text{oder } s \rightarrow \infty \quad H(\infty) = \lim_{s \rightarrow \infty} \frac{s+3}{s+2} = 1)$$

$$\text{Endwert: } \psi(\infty, 0, \nabla) = \lim_{t \rightarrow \infty} \nabla(t) \left(\frac{3}{2} - \frac{e^{-2t}}{2} \right) = \frac{3}{2}$$

$$(\text{oder } s \rightarrow 0 \quad H(0) = \frac{3}{2})$$

$$\frac{3}{2} \nearrow \quad D_1 \psi(0, 0, \nabla) = \frac{-2}{2} e^{-2 \cdot 0} = 1 //$$



$$D_1 \psi(0, 0, \nabla) > 0.$$

$$6.3 \text{ Aufgabe} \quad H(s) = \frac{1}{ms^2 + \gamma s + k} \quad m, \gamma, k > 0$$

i) Regelungsnormalform $H(s)$:

$$h(s) = \frac{b_n s^n + \dots + b_1 \cdot s + b_0}{s^n + a_{n-1} s^{n-1} + \dots + a_1 s + a_0},$$

$$B = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix}$$

$$C = (b_0 - b_n a_0, b_1 - b_n a_1, \dots), \quad D = b_n$$

$$A = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \ddots & & & & \\ 0 & 0 & 0 & \dots & 1 \\ -a_0 & -a_1 & -a_2 & \dots & -a_{n-1} \end{bmatrix}$$

$$H(s) = \frac{1}{ms^2 + ps + k} = \frac{\gamma_m}{s^2 + \frac{p}{\gamma_m}s + \frac{k}{\gamma_m}} \quad \begin{array}{l} b_0 = \gamma_m \\ a_0 = k/m \\ a_1 = p/\gamma_m \end{array}$$

$$A = \begin{bmatrix} 0 & 1 \\ -\gamma_m & -p/\gamma_m \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad C = \begin{bmatrix} \gamma_m & 0 \end{bmatrix} \quad D = 0$$

ii) $G(s) = \frac{s^2}{ms^2 + ps + k}$, Regelungsnormalform

$$G(s) = \frac{s^2}{ms^2 + ps + k} = \frac{s^2/m}{s^2 + \frac{p}{\gamma_m}s + \frac{k}{\gamma_m}} \quad \begin{array}{l} b_2 = \gamma_m \\ a_2 = k/m \\ a_1 = p/\gamma_m \end{array}$$

$$A = \begin{bmatrix} 0 & 1 \\ -\gamma_m & -p/\gamma_m \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad C' = \begin{bmatrix} -\gamma_m^2 & -p/\gamma_m^2 \end{bmatrix} \quad D = \gamma_m$$

6.4 Aufgabe $A = \begin{pmatrix} -3 & 0 \\ 0 & -1 \end{pmatrix}$, $B = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$, $C = \begin{pmatrix} 1 & 0 \end{pmatrix}$, $D = 0$

i) $H(s) = C(s\text{id} - A)^{-1}B + D^0$

$$(s\text{id} - A) = \begin{bmatrix} s+3 & 0 \\ 0 & s+1 \end{bmatrix}, (s\text{id} - A)^{-1} = \frac{1}{(s+3)(s+1)} \begin{bmatrix} s+1 & 0 \\ 0 & s+3 \end{bmatrix}$$

$$H(s) = \frac{1}{(s+3)(s+1)} \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} s+1 & 0 \\ 0 & s+3 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \frac{1}{(s+3)} //$$

ii) $u(t) = \cos(3t)$ $u(t) = \operatorname{Re}(e^{3it})$, $\tilde{u} = e^{3it}$

$$y(t) = \operatorname{Re}(\tilde{y}(t)), \quad \tilde{y}(t) = H(\tilde{u}) \tilde{u}(t)$$

Eigenwerte von A: $-1, -3 \neq 3i$: 1. Bedingung erfüllt.

$$\tilde{y}(t) = H(3i)\tilde{u}(t) \Rightarrow H(3i) = \frac{1}{3i+3} = \frac{3i-3}{9i^2-9} = -\frac{1}{6}(i-1)$$

$$H(3i) = -\frac{1}{6}(e^{\frac{\pi i}{2}-1}) \quad (e^k = \cos(k) + i \sin(k))$$

$$y(t) = \operatorname{Re}(\tilde{y}(t)) = \operatorname{Re}\left(-\frac{1}{6}(e^{\frac{\pi i}{2}-1}) \cdot e^{3it}\right) = \operatorname{Re}\left(-\frac{1}{6}(e^{(5\pi/2+3t)i} - e^{3it})\right)$$

$$y(t) = \frac{1}{6}(\cos(3t) - \cos(3t + \pi/2)) //$$