

Kolloquium Angewandte Mathematik  
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Prof. Matthias Gerdts (LRT1)  
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## Vortragsankündigung

Am **Freitag, den 20.01.2017**, halten **um 14:00 Uhr**

Robert Baier und Wolfgang Riedl  
(U Bayreuth)

einen Gastvortrag über das Thema

### **Adaptive Calculation of Reachable Sets by Distance Functions, OCP Solvers and Subdivision**

Der Vortrag findet im **Raum 1401** in **Gebäude 33** statt.

#### **Vortragszusammenfassung**

Several applications require not only the knowledge of one optimal trajectory but the knowledge of the behaviour of all trajectories and a good approximation of all end points of feasible trajectories at a given end time forming the reachable set. Reachable sets of nonlinear state-constrained control problems with bounded controls can be calculated by various approaches, e.g., by solving partial differential equations and level set approaches, by iterative set-valued Runge-Kutta methods based on boxes in state-space or by overestimating methods.

This talk suggests an adaptive method based on optimization solvers. By solving a series of parametric optimal control problems with a varying objective function, suitable OCP solver like OCPID-DAE1, WORHP or Ipopt can be applied for the original set-valued problem. In this approach, the feasible set equals the reachable set of the control problem and the optimal value involves the distance function of a varying grid point to the (yet unknown) reachable set.

Applying a subdivision technique to this method yields rather simple convergence proofs, a refining overestimation of the reachable set by collection of boxes and an adaptive implementation that outperforms the algorithm if applied only with a regular state space discretization. As applications lower-dimensional projected reachable sets of a robot model and a single-track model for collision avoidance with more than three states and two controls are computed. Features and possible speedups of the algorithm by parallelization are also demonstrated.

**Alle Interessierten sind dazu herzlich eingeladen.**